



Summary

The following software shows how to find the median value of a bunch of data points.

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\ ***** MEDIAN WINDOW SMOOTHING *****  
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\  
\ We have found this median smoothing to be a mathematically robust, noise-  
\ immune and well-behaved way to find the median value of a collection of data  
\ points. The longer the buffer size you select, the stronger the filtering and  
\ the longer the \ delay in response to changing inputs. This algorithm can be  
\ implemented in fixed point form for faster  
\ computation. In addition, you may decide to skip the secondary filtering  
\ associated with the 2ND.BUFFER; this speeds up the algorithm a bit at the  
\ expense of some more \ noise.  
\ To use: call DIM MEDIAN.BUFFERS to initialize the buffers, then call SMOOTH  
\ when each data point is taken. SMOOTH returns the most recent median value.
```

DECIMAL

```
13 CONSTANT WINDOW.SIZE          \ buffer size; MUST BE ODD!  
\ startup delay >= size/2 sample times  
MATRIX: MEDIAN.BUFFER            \ row buffer, holds sorted samples  
  
WINDOW.SIZE 2/ CONSTANT MEDIAN.INDEX      \ median is in middle spot in buf  
  
MATRIX: 2ND.BUFFER                \ row buffer for secondary averaging of median  
WINDOW.SIZE 2/ CONSTANT 2ND.BUFFER.SIZE  
VARIABLE 2ND.BUFFER.POINTER      \ column index  
  
: INIT.MEDIAN.FILTER ( -- )  
  ' MEDIAN.BUFFER ZERO.MATRIX  
  ' 2ND.BUFFER ZERO.MATRIX  
  2ND.BUFFER.POINTER OFF  
  ;  
  
: DIM.MEDIAN.BUFFERS ( -- )  
  \ dims and inits all to zeros at startup  
  1 WINDOW.SIZE ' MEDIAN.BUFFER DIMMED  
  \ Initialize a secondary buffer of size N/2. This buffer maintains the  
  \ last N/2 medians found so that they can be averaged for output.  
  1 2ND.BUFFER.SIZE ' 2ND.BUFFER DIMMED  
  INIT.MEDIAN.FILTER  
  ;
```

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: FIND.INSERTION.POINT ( r -- n )
\ the input r is the new floating point value to be inserted in the buffer and
\ the output n is the index where it should be inserted. Finds the location to
\ insert a number, r, into the buffer so that the buffer values are always in
\ increasing order.
WINDOW.SIZE LOCALS{ &Insertion.Point } ( r -- )
WINDOW.SIZE 0
DO   FDUP \ duplicate the number
    0 I MEDIAN.BUFFER F@ F< \ compare it to each buffer entry in turn
    IF I TO &Insertion.Point \ and leave the loop
        LEAVE
    ENDIF
LOOP
FDROP
&Insertion.Point
;

: INSERT ( r \ n -- )
\ r is the number to be inserted; n is the Insertion.Point If n <=
\ WINDOW.SIZE/2 inserts r into the buffer at n after shifting elements at
\ position n and greater up to greater indices. If n > WINDOW.SIZE/2 inserts r
\ into the buffer at n-1 after shifting elements at position n-1 and less down
\ to lesser indices.
LOCALS{ &Insertion.Point } ( r -- )
&Insertion.Point MEDIAN.INDEX <=
IF &Insertion.Point WINDOW.SIZE 2-
    DO 0 I MEDIAN.BUFFER F@ \ shift to the right
        0 I 1+ MEDIAN.BUFFER F!
    -1 +LOOP
    0 &Insertion.Point MEDIAN.BUFFER F! \ emplace new number
ELSE
    &Insertion.Point 1- 0
    DO 0 I 1+ MEDIAN.BUFFER F@ \ shift to the left
        0 I MEDIAN.BUFFER F!
    LOOP
    0 &Insertion.Point 1- MEDIAN.BUFFER F! \ emplace new number
ENDIF
;

```

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: SMOOTH ( r1 -- r2 )
\ Inserts the input r1 into the Buffer & fetches the Buffer's middle value,
\ an estimate of the running median, for insertion into the 2nd Buffer,
\ and averages all values of the 2nd Buffer to yield the output r2.
    FDUP FIND. INSERTION. POINT ( r\n -- )
    INSERT ( -- ) \ Insert new number into buffer
\ Fetch the center number of the buffer and place it into the second buffer
    0 MEDIAN. INDEX MEDIAN. BUFFER F@ ( estimated. median -- )
\ we could stop here if pressed for time, but we add another layer of
\ filtering:
    0 2ND. BUFFER. POINTER @ 2ND. BUFFER F!
    2ND. BUFFER. POINTER @ 1+ 2ND. BUFFER. SIZE MOD
    2ND. BUFFER. POINTER ! \ update pointer to circular 2nd. buffer
    ' 2ND. BUFFER MATRIX. SUM
    2ND. BUFFER. SIZE FLOT F/ ( averaged. median -- )
;

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